
TIP120

Motion Controller with Incremental Encoder Interface

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User Manual

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TIP120-10

2 axes motion controller using LM628 with incremental encoder interface

TIP120-11

1 axis motion controller using LM628 with incremental encoder interface

TIP120-20

2 axes motion controller using LM629 with incremental encoder interface

TIP120-21

1 axis motion controller using LM629 with incremental encoder interface

TIP120-30

2 axes motion controller using LM628 and LM629 with incremental encoder interface

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Style Conventions

Hexadecimal characters are specified with prefix 0x, i.e. 0x029E (that means hexadecimal value 029E).

For signals on hardware products, an 'Active Low' is represented by the signal name with # following, i.e. IP_RESET#.

Access terms are described as:

W	Write Only
R	Read Only
R/W	Read/Write
R/C	Read/Clear
R/S	Read/Set

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1.0	First Issue	November 1999
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Table of Contents

1	PRODUCT DESCRIPTION	6
2	TECHNICAL SPECIFICATION	7
3	ID PROM CONTENTS	8
4	IP ADDRESSING	9
	4.1 I/O Addressing.....	9
	4.2 Control / Status Register	10
	4.3 Data Register	10
	4.4 Output Register	10
	4.5 Input Register	10
	4.6 Interrupt Status Register	11
	4.7 Interrupt Control Register	11
	4.8 Interrupt Enable Register	12
	4.9 Interrupt Vector Register.....	12
5	PROGRAMMING HINTS	13
6	PIN ASSIGNMENT – I/O CONNECTOR	14

Table of Figures

FIGURE 1-1 : BLOCK DIAGRAM.....	6
FIGURE 2-1 : TECHNICAL SPECIFICATION.....	7
FIGURE 3-1 : ID PROM CONTENTS	8
FIGURE 4-1 : REGISTER SET	9
FIGURE 4-2 : OUTPUT REGISTER	10
FIGURE 4-3 : INPUT REGISTER	10
FIGURE 4-4 : INTERRUPT STATUS REGISTER	11
FIGURE 4-5 : INTERRUPT CONTROL REGISTER.....	11
FIGURE 4-6 : INTERRUPT ENABLE REGISTER	12
FIGURE 4-7 : INTERRUPT VECTOR REGISTER.....	12
FIGURE 6-1 : PIN ASSIGNMENT I/O CONNECTOR.....	14

1 Product Description

The TIP120 family of IndustryPack® compatible modules is designed for motion control applications using incremental encoders as position feedback. There are five board options available:

The TIP120-1x is a one or two axes motion control IP based on the LM628 controller from National Semiconductor providing a ±10V output signal by a 12 bit D/A converter. The ±10V output signal is buffered by an operational amplifier which is able to drive unlimited capacitive loads. This signal can be used to drive the power amplifier of the motor drive system.

The TIP120-2x is a one or two axes motion control IP based on the LM629 controller from National Semiconductor providing an 8 bit sign-magnitude PWM output signal. The PWM output signal is buffered by a TTL driver capable up to +/- 24mA. This signal can be used for directly driving H switches.

The TIP120-30 is a two axes motion control IP based on the LM628 controller from National Semiconductor for axis 1 providing a ±10V output signal by a 12 bit D/A converter and based on the LM629 controller from National Semiconductor for axis 2 offering an 8 bit sign / magnitude PWM output signal. The +/-10V output signal is buffered by an operational amplifier which is able to drive unlimited capacity loads. This signal can be used to drive the power amplifier of the motor drive system. The PWM output is buffered by a TTL driver capable up to +/-24mA. This signal can be used for directly driving H switches.

The position feedback is provided by an incremental encoder interface. The level of the encoder signals can be TTL or RS422.

The LM628 / LM629 used on the TIP120-xx are dedicated motion control processors designed for use with a variety of DC and brushless DC servo motors, and other servomechanisms which provide a quadrature (quadruple) incremental position feedback signal.

The LM628 / LM629 perform the intensive, real-time computational tasks required for high performance digital motion control. The host control software interface is facilitated by a high-level command set.

Three isolated 24V DC digital inputs are available for user functionality. The function for the three inputs may be limit switches and emergency stop input. A floating optical output can be controlled by software, for example as enable signal for the motor power amplifier.

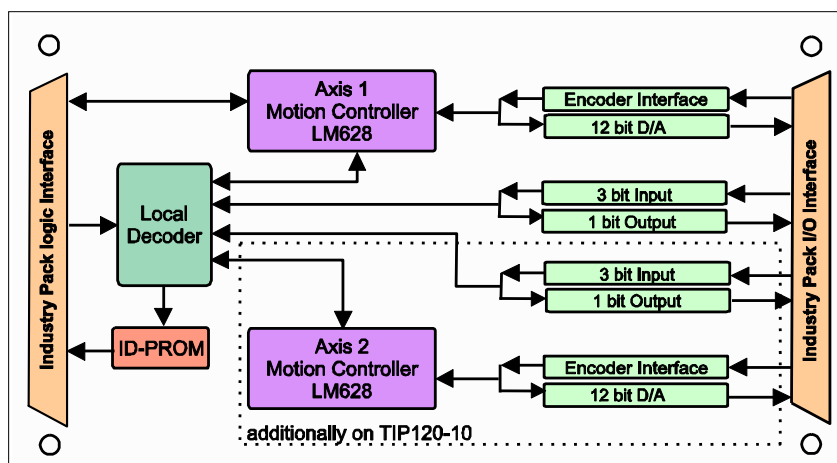


Figure 1-1 : Block Diagram

2 Technical Specification

IP Interface	
Interface	Single Size IndustryPack® Logic Interface compliant to ANSI/VITA 4-1995
ID ROM Data	Format I
I/O Space	Used (LM62x Registers, Interrupt Vector Register)
Memory Space	Not Used
Interrupts	Int1 used (LM62x Axis 1) / Int2 used (LM62x Axis 2)
DMA	Not supported
Clock Rate	8 MHz
Module Type	Type I
Wait states	LM62x Registers: Read cycle 1 wait state, write cycle no wait states All others: no wait states
Interrupt	Vectored interrupts
On Board Devices	
Motion Controller	National LM628 for +/-10V output signal: D/A converter: 12 bit DAC, +/-10V output Output OP: +/-10V at +/-10mA, unlimited capacitive load National LM629 for PWM output signal (TTL): 8 bit sign-magnitude PWM, TTL signal +/-24mA
I/O Interface	
Optical Isolated I/O	Three 24V DC inputs, protected against confusing the pole for each axis, input threshold 8.5V to 14V. One software controlled floating output for each axis (transistor or optocoupler).
Encoder Input	Quadrature encoder interface for RS422 or TTL level with phase A, phase B and index Minimum pulse width (high and low) : 2µs
Interface Connector	50-conductor flat cable
Physical Data	
Power Requirements	200mA typical @ +5V DC 40mA typical @ +12V DC 40mA typical @ -12V DC
Temperature Range	Operating 0 °C to +70 °C Storage -25°C to +125°C
MTBF	TIP120-10: 285000 h
Humidity	5 – 95 % non-condensing

Figure 2-1 : Technical Specification

3 ID Prom Contents

Offset	Function	Value
0x01	ASCII 'I'	0x49
0x03	ASCII 'P'	0x50
0x05	ASCII 'A'	0x41
0x07	ASCII 'C'	0x43
0x09	Manufacturer ID	0xB3
0x0B	Model Number	0x1E
0x0D	Revision	0x10
0x0F	Reserved	0x00
0x11	Driver-ID Low - Byte	0x00
0x13	Driver-ID High - Byte	0x00
0x15	Number of bytes used	0x0D
0x17	CRC	TIP120-10: 0x72 TIP120-11: 0x53 TIP120-20: 0x8D TIP120-21: 0xAC TIP120-30: 0xC7
0x19	Board Option	TIP120-10: 0x0A TIP120-11: 0x0B TIP120-20: 0x14 TIP120-21: 0x15 TIP120-30: 0x1E
...	Not used	...
0x3F	-	0x00

Figure 3-1 : ID PROM Contents

4 IP Addressing

4.1 I/O Addressing

The complete register set of the TIP120 accessible in the IP I/O space.

Offset	Symbol	Description	Size (Bit)
Axis 1 Registers			
0x01	CONTROL1/STATUS1	Control/Status Register LM628/LM629	8
0x03	DATA1	Data Register LM628/LM629	8
0x05	OUTPUT1	Output Register Control Switch	8
0x07	INPUT1	Input Register Control Switches	8
0x09	INTSTAT1	Interrupt Status Register	8
0x0B	INTCR1	Interrupt Control Register	8
0x0D	INTENA1	Interrupt Enable Register	8
0x0F	Reserved		
Axis 2 Registers			
0x11	CONTROL2/STATUS2	Control/Status Register LM628/LM629	8
0x13	DATA2	Data Register LM628/LM629	8
0x15	OUTPUT2	Output Register Control Switch	8
0x17	INPUT2	Input Register Control Switches	8
0x19	INTSTAT2	Interrupt Status Register	8
0x1B	INTCR2	Interrupt Control Register	8
0x1D	INTENA2	Interrupt Enable Register	8
0x1F	Reserved		
0x21	INTVEC	Interrupt Vector Register	8

Figure 4-1 : Register Set

4.2 Control / Status Register

The Control Register of the TIP120 is a byte wide write only register. An access to the Control Register will select the next command to the motion controller. For further information about the command settings of the motion controller please refer to the LM628 / LM629 data sheet which is part of the TIP120-ED Engineering Documentation.

The Status Register of the TIP120 is a byte wide read only register. For further information about the Status Register please refer to the LM628 / LM629 data sheet which is part of the TIP120-ED Engineering Documentation.

4.3 Data Register

The Data Register of the TIP120 is a byte wide read/write register. An access to the Data Register requires an access to the Control Register first. The motion controller uses a multiplexed 8 bit asynchronous host interface. A 16 bit data read/write to the motion controller requires two 8 bit accesses. The first access takes the high byte and the second access the low byte of the 16 bit word. For further information about the data settings of the motion controller please refer to LM628 / LM629 data sheet which is part of the TIP120-ED Engineering Documentation.

4.4 Output Register

The Output Register of the TIP120 is a byte wide read/write register. The Output Register controls an optical isolated open collector output / floating switch. The output switch may be used for an additional axis enable control.

Bit	Symbol	Description	Access	Reset Value
7:1		Read as '0' Write : Don't care		
0	OUT1	OUTPUT1 Control Axis X 0 : Open Collector Output Driver OFF / Floating Switch Open 1 : Open Collector Output Driver ON / Floating Switch Closed	R/W	0

Figure 4-2 : Output Register

4.5 Input Register

The Input Register of the TIP120 is a byte wide read register. The Input Register shows the actual level at the TIP120 input pins. The inputs may be used for limit switches and emergency stop detection for each axis.

Bit	Symbol	Description	Access	Reset Value
7:3		Read as '0'		
2	IN3	INPUT 1-3 Status of Axis X 0 : Input x not active 1 : Input x active	R	
1	IN2			
0	IN1			

Figure 4-3 : Input Register

4.6 Interrupt Status Register

The Interrupt Status Register of the TIP120 is a byte wide mixed access register. The Interrupt Status Register reflects the interrupt status of the three TIP120 inputs and the TIP120 LM62x motion controller interrupt. If an interrupt is pending, the corresponding Interrupt Status Register bit is read as '1'. To quit the interrupts for the TIP120 inputs, write a '1' to the corresponding bit of the Interrupt Status Register. The LM62x motion controller interrupts must be acknowledged by programming the LM62x. For more information please refer to the LM628 Programming Guide which is part of the TIP120-ED Engineering Documentation.

Bit	Symbol	Description	Access	Reset Value
7:4		Read as '0' Write : Don't care		
3	INT_LM	Interrupt LM62x of Axis X 0 : No active interrupt 1 : Active interrupt	R	
2	INT_IN3	Interrupt INPUT 1-3 of Axis X 0 : No active interrupt 1 : Active interrupt Write '1' to clear interrupt.	R/C	
1	INT_IN2			
0	INT_IN1			

Figure 4-4 : Interrupt Status Register

The input interrupts are only active if the corresponding enable bit in the Interrupt Enable Register is set to '1'. The interrupt status of the LM62x can be read at any time.

**NOTE : After RESET# a LM62x interrupt is pending !!!
The user must execute the LM62x 'Reset Interrupt' routine. For details please refer to the LM62x Programming Guide which is part of the TIP120-ED Engineering Documentation.**

4.7 Interrupt Control Register

The Interrupt Control Register of the TIP120 is a byte wide read/write register. The Interrupt Control Register controls which signal transition forces an interrupt for the TIP120 inputs.

Bit	Symbol	Description	Access	Reset Value
7:3		Read as '0'		
2	INT_IN3_POL	Transition Select INPUT 1-3 of Axis X 0 : Interrupt Request on High to Low Transition 1 : Interrupt Request on Low to High Transition	R/W	000
1	INT_IN2_POL			
0	INT_IN1_POL			

Figure 4-5 : Interrupt Control Register

4.8 Interrupt Enable Register

The Interrupt Enable Register of the TIP120 is a byte wide read/write register. The Interrupt Enable Register enables or disables the various interrupt sources.

Bit	Symbol	Description	Access	Reset Value
7:4		Read as '0' Write : Don't care		
3	INT_LM_EN	Interrupt Enable LM62x of Axis X 0 : Interrupt disabled 1 : Interrupt enabled	R/W	0
2	INT_IN3_EN	Interrupt Enable INPUT1-3 of Axis x 0 : Interrupt disabled 1 : Interrupt enabled	R/W	000
1	INT_IN2_EN			
0	INT_IN1_EN			

Figure 4-6 : Interrupt Enable Register

4.9 Interrupt Vector Register

The Interrupt Vector Register of the TIP120-xx is a byte wide read/write register. It holds the interrupt vector passed to the CPU during interrupt acknowledge cycles.

Bit	Symbol	Description	Access	Reset Value
7:1	INT_VEC	Higher bits of 8 bit Interrupt Vector, loaded by software.		
0		Bit is generated by the TIP120 hardware. 0 : Interrupt Axis 1 1 : Interrupt Axis 2 Axis 1 generates interrupts on INTREQ0#, Axis 2 generates interrupts on INTREQ1# of the IP bus.	R/W	

Figure 4-7 : Interrupt Vector Register

5 Programming Hints

The LM628 Motion Controller can operate in an 8 bit DAC mode or in a 12bit DAC mode. The LM628 default mode after power-up or reset is the 8 bit DAC mode.

The TIP120 does only support the 12 bit DAC mode. For board options with the LM628 Motion Controller, the user must issue the PORT12 command early in the initialization phase to set the LM628 DAC mode to 12 bit. Please see the LM628 documentation for details.

For a detailed description of the LM628 / LM629 motion controller please refer to the following documents which are part of the TIP120-ED Engineering Documentation:

- Data Sheet LM628 / LM629 Precision Motion Controller
- LM628 / LM629 User Guide (AN-706)
- LM628 Programming Guide (AN-693)

6 Pin Assignment – I/O Connector

Pin	Function	Pin	Level
1	INPUT1 Axis 1 +	26	INPUT1 Axis 2 +
2	INPUT1 Axis 1 -	27	INPUT1 Axis 2 -
3	INPUT2 Axis 1 +	28	INPUT2 Axis 2 +
4	INPUT2 Axis 1 -	29	INPUT2 Axis 2 -
5	INPUT3 Axis 1 +	30	INPUT3 Axis 2 +
6	INPUT3 Axis 1 -	31	INPUT3 Axis 2 -
7	OUPUT1 Axis 1+	32	OUPUT1 Axis 2+
8	OUPUT1 Axis 1 -	33	OUPUT1 Axis 2 -
9	NC	34	NC
10	NC	35	NC
11	AGND	36	AGND
12	PWM Output Axis 1 MAG	37	PWM Output Axis 2 MAG
13	PWM Output Axis 1 SIGN	38	PWM Output Axis 2 SIGN
14	DAC Output Axis 1	39	DAC Output Axis 2
15	DAC GND Axis 1	40	DAC GND Axis 2
16	AGND	41	AGND
17	Phase A Axis 1	42	Phase A Axis 2
18	Phase A Axis 1#	43	Phase A Axis 2#
19	Phase B Axis 1	44	Phase B Axis 2
20	Phase B Axis 1#	45	Phase B Axis 2#
21	Phase Index Axis 1	46	Phase Index Axis 2
22	Phase Index Axis 1#	47	Phase Index Axis 2#
23	AGND	48	AGND
24	NC	49	NC
25	NC	50	NC

Figure 6-1 : Pin Assignment I/O Connector