

NAMC-ECAT AMC EtherCAT Slave Module Technical Reference Manual V1.1 HW Revision 1.1



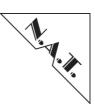


The NAMC-ECAT has been designed by:

N.A.T. GmbH Konrad-Zuse-Platz 9 D-53227 Bonn

Phone: ++49 / 228 / 965 864 - 0 Fax: ++49 / 228 /965 864 - 10

E-Mail: support@nateurope.com Internet: http://www.nateurope.com



Disclaimer

The following documentation, compiled by N.A.T. GmbH (henceforth called N.A.T.), represents the current status of the product's development. The documentation is updated on a regular basis. Any changes which might ensue, including those necessitated by updated specifications, are considered in the latest version of this documentation. N.A.T. is under no obligation to notify any person, organization, or institution of such changes or to make these changes public in any other way.

We must caution you, that this publication could include technical inaccuracies or typographical errors.

N.A.T. offers no warranty, either expressed or implied, for the contents of this documentation or for the product described therein, including but not limited to the warranties of merchantability or the fitness of the product for any specific purpose.

In no event will N.A.T. be liable for any loss of data or for errors in data utilization or processing resulting from the use of this product or the documentation. In particular, N.A.T. will not be responsible for any direct or indirect damages (including lost profits, lost savings, delays or interruptions in the flow of business activities, including but not limited to, special, incidental, consequential, or other similar damages) arising out of the use of or inability to use this product or the associated documentation, even if N.A.T. or any authorized N.A.T. representative has been advised of the possibility of such damages.

The use of registered names, trademarks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations (patent laws, trade mark laws, etc.) and therefore free for general use. In no case does N.A.T. guarantee that the information given in this documentation is free of such third-party rights.

Neither this documentation nor any part thereof may be copied, translated, or reduced to any electronic medium or machine form without the prior written consent from N.A.T. GmbH.

This product (and the associated documentation) is governed by the N.A.T. General Conditions and Terms of Delivery and Payment.

Note:

The release of the Hardware Manual is related to a certain HW board revision given in the document title. For HW revisions earlier than the one given in the document title please contact N.A.T. for the corresponding older Hardware Manual release.



Table of Contents

L	JIST OF TABLES	6
L	LIST OF FIGURES	6
C	CONVENTIONS	7
1	INTRODUCTION	8
2	BOARD FEATURES	11
	2.1 SAFETY NOTE 2.2 INSTALLATION PREREQUISITES AND REQUIREMENTS 2.2.1 Requirements 2.2.2 Power supply 2.2.3 Automatic Power Up 2.3 STATEMENT ON ENVIRONMENTAL PROTECTION 2.3.1 Compliance to RoHS Directive 2.3.2 Compliance to WEEE Directive 2.3.3 Compliance to CE Directive 2.3.4 Product Safety 2.4 LOCATION OVERVIEW	
3	FUNCTIONAL BLOCKS	17
	3.1 ETHERCAT SLAVE CONTROLLER (ESC) 3.2 FPGA 3.3 PCI EXPRESS INTERFACE 3.4 AMC CLOCK INTERFACE 3.5 IPMB INTERFACE 3.6 I ² C DEVICES 3.7 AMC PORT DEFINITION 3.8 FRONT PANEL AND LEDS	
4	CONNECTORS	22
	4.1 CONNECTOR OVERVIEW 4.2 AMC CONNECTOR J1 4.3 CONNECTOR JP1: IPMI-µC PROGRAMMING PORT 4.4 CONNECTOR JP2: LATTICE FPGA PROGRAMMING PORT 4.5 HOT SWAP SWITCH SW1 4.6 THE FRONT PANEL CONNECTORS (S1 – S3) 4.6.1 The Ethernet Connector S1 4.6.2 The Ethernet Connector S2 4.6.3 The Ethernet Connector S3	23 25 25 26 26 26 26 27
5		
	5.1.1 FPGA GP Registers/Status	

NAMC-ECAT – Technical Reference Manual



AP	PENDIX A:	REFERENCE DOCUMENTATION	
6	KNOWN	BUGS / RESTRICTIONS	
	5.1.1.9	ESC Register	3
	5.1.1.8	SPI interface register to FPGA PROM	
	5.1.1.7	SPI interface register to FPGA PROM	
	5.1.1.6	FPGA Version Register FPGA ID_1 Register FPGA ID_2 Register FPGA BOARD_ID Register FPGA Reset Register	
	5.1.1.5	FPGA BOARD ID Register	
	5.1.1.4	FPGA ID 2 Register.	
	5.1.1.3	FPGA ID 1 Register	
	5.1.1.2	FPGA Version Register	



List of Tables

Table 1:	List of used abbreviations	7
Table 2:	NAMC-ECAT Features	11
Table 3:	AMC Port Definition	20
Table 1:	LED Functionality	21
Table 2:	AMC Connector J1	23
Table 1:	Atmel Programming Port	25
Table 1:	Lattice programming port	25
Table 2:	Pin Assignment of the Front-panel Connectors S1 (Ethernet)	26
Table 3:	Pin Assignment of the Front-panel Connectors S2 (Ethernet)	26
Table 4:	Pin Assignment of the Front-panel Connectors S3 (Ethernet)	27
Table 1:	FPGA Memory Map	28
Table 1:	PCB Version Register	28
Table 1:	FPGA Version Register	29
Table 2:	FPGA ID_1 Register	29
Table 3:	FPGA ID_2 Register	
Table 4:	FPGA BOARD_ID Register	29
Table 5:	FPGA Reset Register	30
Table 1:	ESC Register	30
List of	Figures	
Figure 1:	NAMC-ECAT Block Diagram (3 Ports)	9
Figure 2:	NAMC-ECAT Block Diagram (2 Ports)	9
Figure 3:	Location diagram of the NAMC-ECAT	16
Figure 4:	EtherCAT Slave Controller Block Diagram	17
Figure 5:	I ² C Structure of the NAMC-ECAT (a)	19
Figure 6:	I ² C Structure of the NAMC-ECAT (b)	19
Figure 7:	Front Panel (3 Port)	21
Figure 8:	Front Panel (2 Port)	
Figure 9:	Connectors of the NAMC-ECAT	22



Conventions

If not otherwise specified, addresses and memory maps are written in hexadecimal notation, identified by 0x.

Table 1 gives a list of the abbreviations used in this document:

Table 1: List of used abbreviations

Abbreviation	Description	
_	21.44	
b	Bit, binary	
В	Byte	
AMC	Advanced Mezzanine Card	
ASIC	Application Specific Integrated Circuit	
CPU	Central Processing Unit	
EPU	EtherCAT Processing Unit	
ESC EhterCAT Slave Controller		
EtherCAT Ethernet for Control Automation Technology		
FMMU Fieldbus Memory Management Unit		
FPGA Field Programmable Gate Array		
μTCA	Micro Telecommunications Computing Architecture	
PCI	Peripheral Component Interconnect	
PCIe	PCI Express	
PDI	Process Data Interface	
RAM	Random Access Memory	
ROM	Read Only Memory	



1 Introduction

The NAMC-ECAT is an EtherCAT (Ethernet for Control Automation Technology) interface card in AMC (Advanced Mezzanine Card) form factor. The slave card has the task to connect a flexible, scalable and powerful Micro Telecommunications Computing Architecture (μ TCA)-System to the high speed EtherCAT fieldbus. Using μ TCA as dedicated slave nodes in an EtherCAT network adds a new dimension of intelligent and scalable nodes to this industrial automation network. This requires the utilization of the EtherCAT interface card (NAMC-ECAT).

Key component of the EtherCAT slave card NAMC-ECAT is the ESC (EtherCAT Slave Controller) as Interface between the EtherCAT bus and the user application within the μTCA -system. As ESC the EtherCAT-ASIC ET1100 from Beckhoff Automation is used. The ESC has an 8kByte Dual Port RAM to exchange data between the EtherCAT network and the application.

The NAMC-ECAT is available as a single mid or a single full-size module. Form the point of view of the EtherCAT fieldbus there are two different versions regarding the EtherCAT interfaces. The slave card is available in a two or three port version.

The NAMC-ECAT has the following major features implemented on-board:

- Ports: 3/2 x RJ45 EtherCAT interfaces
- RAM [KByte]: 8
- Fieldbus Memory Management Unit (FMMU): 8
- SyncManagers: 8
- Distributed Clocks: 64 bit
- Process Data Interface (PDI): 16/8 bit synchronous μController
- 1 Lane PCI Express Interface Rev. 1.1
- Configuration/Control via PCIe or via EtherCAT



Figure 1 shows a detailed block diagram of the NAMC-ECAT (3 Ports).

EEPROM EEPROM SPI **PHY** AMC plug-in 8 bit PCI to PCIe **EtherCAT Slave FPGA** PHY **Bridge** Controller ECAT **PHY** Leds MMC Leds I²C

Figure 1: NAMC-ECAT Block Diagram (3 Ports)

Figure 2 shows a detailed block diagram of the NAMC-ECAT (2 Ports).

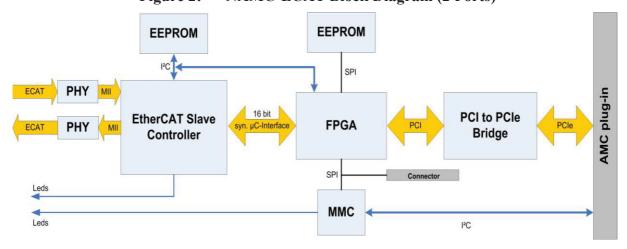


Figure 2: NAMC-ECAT Block Diagram (2 Ports)



Board Features

• EtherCAT Ports

There are 2 or 3 EtherCAT interfaces available on the NAMC-ECAT. They are realized by the Ethernet connectors and the PHYs which are connected to the EtherCAT Slave Controller (ESC). For the connection to the AMC based EtherCAT slave card a standard Ethernet patch cable is required.

• EtherCAT Slave Controller (ESC)

The central component on the NAMC-ECAT is the EtherCAT slave controller (ET1100). The ESC is responsible for the EtherCAT communication between the EtherCAT fieldbus and the slave application. The ESC contains the necessary components (e.g. EtherCAT Processing Unit (EPU), FMMU, SyncManager, RAM, etc.) for the data transfer between the fieldbus and the FPGA. Thereby a 16 or 8 bit synchronous µController interface is used (depending on the number of available ports on the NAMC-ECAT).

• Backplane Interface

PCIe: The NAMC-ECAT includes a x1-PCI Express interface. This is

implemented in a PEX8112 PCI-X to PCIe bridge (PLX). The PCI Express interface connects to Port 4 of the Fat Pipe Region of the AMC backplane connector. The implementation of PCIe conforms to the

AMC.1 specification.

IPMB: The NAMC-ECAT implements an IPMB interface which conforms to

the AMC.0 specification.



1.1 Board Specification

Table 2: NAMC-ECAT Features

AMC-Module standard Advanced Mezzanine Card, single width, double height

Front-I/O 3/2 x RJ45 connectors

RAM 8 KByte RAM

Power consumption 3,3V MP 0.1A max

12V 0.7A max.

Environmental

conditions

Temperature (operating): 0°C to +50°C with forced cooling

Temperature (storage): -40° C to $+85^{\circ}$ C

Humidity: 10 % to 90 % rh noncondensing

Standards compliance PICMG AMC.0 Rev. 2.0

PICMG AMC.1 Rev. 1.0

PCI Express Base Specification Rev. 1.1

PICMG SFP.0 Rev. 1.0 (System Fabric Plane Format)

IPMI Specification v2.0 Rev. 1.0

PICMG μTCA.0 Rev. 1.0

ETG.1300 Indicator and Labeling Specification



2 Installation

2.1 Safety Note

To ensure proper functioning of the NAMC-ECAT during its usual lifetime take the following precautions before handling the board.

CAUTION

Electrostatic discharge and incorrect board installation and uninstallation can damage circuits or shorten their lifetime.

- Before installing or uninstalling the NAMC-ECAT read this installation section
- Before installing or uninstalling the **NAMC-ECAT**, read the Installation Guide and the User's Manual of the carrier board used, or of the uTCA system the board will be plugged into.
- Before installing or uninstalling the **NAMC-ECAT** on a carrier board or both in a rack:
 - Check all installed boards and modules for steps that you have to take before turning on or off the power.
 - Take those steps.
 - Finally turn on or off the power if necessary.
 - Make sure the part to be installed / removed is hot swap capable, if you don't switch off the power.
- Before touching integrated circuits ensure to take all require precautions for handling electrostatic devices.
- Ensure that the **NAMC-ECAT** is connected to the carrier board or to the uTCA backplane with the connector completely inserted.
- When operating the board in areas of strong electromagnetic radiation ensure that the module
 - is bolted the front panel or rack
 - and shielded by closed housing



2.2 Installation Prerequisites and Requirements

IMPORTANT

Before powering up

• check this section for installation prerequisites and requirements

2.2.1 Requirements

The installation requires only

- an ATCA carrier board, or a μTCA backplane for connecting the NAMC-ECAT
- power supply
- cooling devices

2.2.2 Power supply

The power supply for the **NAMC-ECAT** must meet the following specifications:

• required for the module: +12V / 0.7A max.

2.2.3 Automatic Power Up

In the following situations the **NAMC-ECAT** will automatically be reset and proceed with a normal power up.

Voltage sensors

The voltage sensor generates a reset

- when +12V voltage level drops below 8V
- when +3.3V voltage level drops below 3.08V

or when the carrier board / backplane signals a PCIe Reset.



2.3 Statement on Environmental Protection

2.3.1 Compliance to RoHS Directive

Directive 2002/95/EC of the European Commission on the "Restriction of the use of certain Hazardous Substances in Electrical and Electronic Equipment" (RoHS) predicts that all electrical and electronic equipment being put on the European market after June 30th, 2006 must contain lead, mercury, hexavalent chromium, polybrominated biphenyls (PBB) and polybrominated diphenyl ethers (PBDE) and cadmium in maximum concentration values of 0.1% respective 0.01% by weight in homogenous materials only.

As these hazardous substances are currently used with semiconductors, plastics (i.e. semiconductor packages, connectors) and soldering tin any hardware product is affected by the RoHS directive if it does not belong to one of the groups of products exempted from the RoHS directive.

Although many of hardware products of N.A.T. are exempted from the RoHS directive it is a declared policy of N.A.T. to provide all products fully compliant to the RoHS directive as soon as possible. For this purpose since January 31st, 2005 N.A.T. is requesting RoHS compliant deliveries from its suppliers. Special attention and care has been paid to the production cycle, so that wherever and whenever possible RoHS components are used with N.A.T. hardware products already.

2.3.2 Compliance to WEEE Directive

Directive 2002/95/EC of the European Commission on "Waste Electrical and Electronic Equipment" (WEEE) predicts that every manufacturer of electrical and electronical equipment which is put on the European market has to contribute to the reuse, recycling and other forms of recovery of such waste so as to reduce disposal. Moreover this directive refers to the Directive 2002/95/EC of the European Commission on the "Restriction of the use of certain Hazardous Substances in Electrical and Electronic Equipment" (RoHS).

Having its main focus on private persons and households using such electrical and electronic equipment the directive also affects business-to-business relationships. The directive is quite restrictive on how such waste of private persons and households has to be handled by the supplier/manufacturer; however, it allows a greater flexibility in business-to-business relationships. This pays tribute to the fact with industrial use electrical and electronical products are commonly integrated into larger and more complex environments or systems that cannot easily be split up again when it comes to their disposal at the end of their life cycles.

NAMC-ECAT - Technical Reference Manual



As N.A.T. products are solely sold to industrial customers, by special arrangement at time of purchase the customer agreed to take the responsibility for a WEEE compliant disposal of the used N.A.T. product. Moreover, all N.A.T. products are marked according to the directive with a crossed out bin to indicate that these products within the European Community must not be disposed with regular waste.

If you have any questions on the policy of N.A.T. regarding the Directive 2002/95/EC of the European Commission on the "Restriction of the use of certain Hazardous Substances in Electrical and Electronic Equipment" (RoHS) or the Directive 2002/95/EC of the European Commission on "Waste Electrical and Electronic Equipment" (WEEE) please contact N.A.T. by phone or e-mail.

2.3.3 Compliance to CE Directive

Compliance to the CE directive is declared. A 'CE' sign can be found on the PCB.

2.3.4 Product Safety

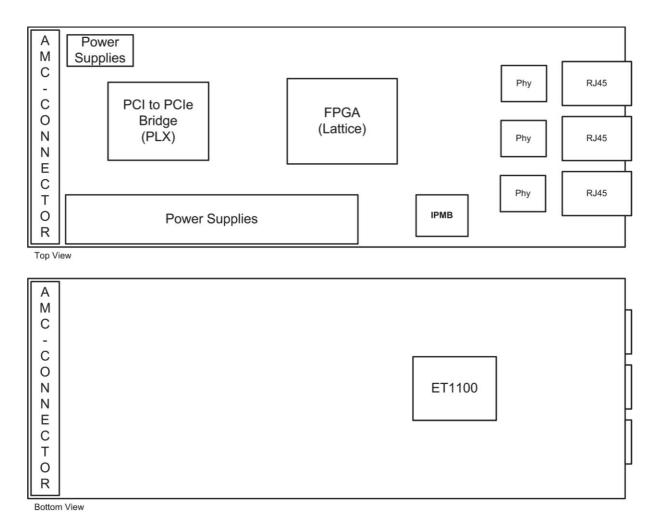
The board complies with EN60950 and UL1950.



2.4 Location Overview

Figure 3 and Figure 4 show the position of important components. Depending on the board type it might be that the board does not include all components named in the location diagram.

Figure 3: Location diagram of the NAMC-ECAT





3 Functional Blocks

The **NAMC-ECAT** can be divided into a number of functional blocks, which are described in the following paragraphs.

3.1 EtherCAT Slave Controller (ESC)

The ESC (ET1100) is an ASIC from Beckhoff Automation that process the EtherCAT protocol in the hardware. It offers various possibilities for the configuration and utilization of the available hardware recourses. In figure 3 you can see the block diagram of the ESC and its configuration.

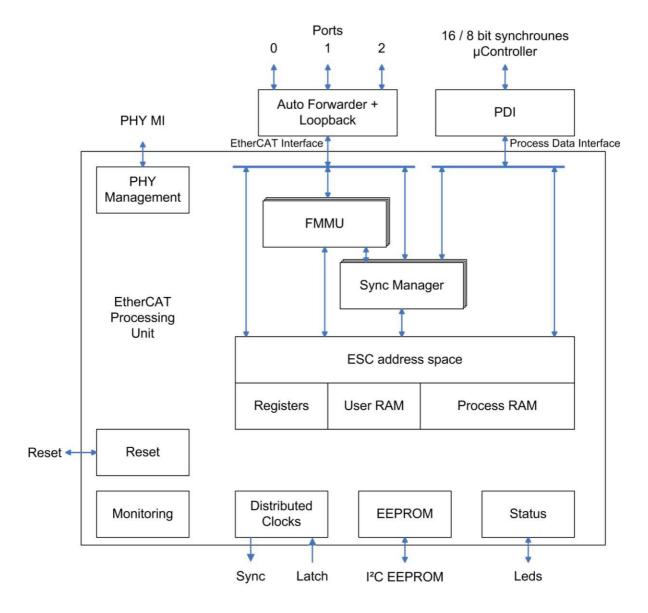


Figure 4: EtherCAT Slave Controller Block Diagram

NAMC-ECAT - Technical Reference Manual



For more details regarding the EtherCAT Slave Controller, its function, features, properties and the allocation of the ESC address space please consider the ET1100 data sheet.

3.2 FPGA

The FPGA implements the following functional blocks:

- PCI interface for management
- 16/8 bit µController interface

3.3 PCI Express Interface

The NAMC-ECAT includes a 1 lane PCI Express interface. This is implemented in a PEX8112 PCI to PCIe bridge (PLX). The PCIe bridge may receive its reference clock either from the Clock 3 port of the AMC backplane connector, or from a local 100 MHz oscillator circuitry (default). The clock source is programmable.

3.4 AMC Clock Interface

AMC backplane clock port Clock 1 is connected to the FPGA, in order to be used as a Telecom standard clock. Clock 1 is only received.

AMC backplane clock port Clock 2 is connected to the FPGA, in order to be used as a Telecom standard reference. Clock 2 may be received from or transmitted to the backplane, in order to become the reference clock for the entire system.

AMC backplane clock port Clock 3 is connected to the PCI → PCIe bridge, in order to be used as a reference clock for PCI Express. Clock 3 is only received. Clock 3 is routed to a multiplexer, which allows programming the clock source of the PCIe line to be either Clock 3, or an internal differential 100 MHz reference clock. In case clock 3 is to be used for a different functionality, it also feeds the FPGA and may be used there for any suitable purpose.

3.5 IPMB Interface

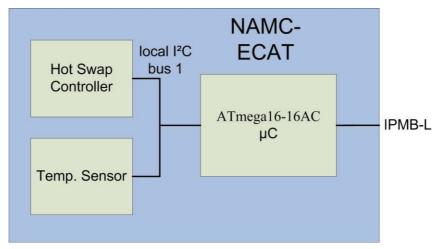
The NAMC-ECAT implements an IPMB interface consisting of an ATmega16-16AC microcontroller and a couple of I2C devices, such as a temperature sensor. The IPMB controller manages also the hot swap functionality and the geographical address as requested by the AMC specification.

3.6 I²C Devices

Two I²C busses connect to the IPMI controller (an ATmega16-16AC microcontroller). The first one is the IPMB bus of the AMC connector. The second I²C bus connects the IPMI controller, the Hot Swap Controller and a temperature sensor. These devices are all powered by IPMB power.

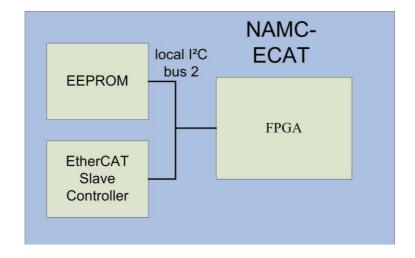


Figure 5: I²C Structure of the NAMC-ECAT (a)



A third I²C bus connects the FPGA and the EEPROM which is necessary for the ESC. The EEPROM can also be accessed via ESC.

Figure 6: I²C Structure of the NAMC-ECAT (b)





3.7 AMC Port Definition

Table 3: AMC Port Definition

	Port No.	AMC Port Mapping Strategy	Ports used as
	CLK1	Strategy	Reference Clock 1
	CLK2	Clocks	Reference Clock 2
	CLK3		Reference Clock 3
Basic Connector	0	Common	Unassigned
mec	1	Options	Unassigned
Con	2	Region	Unassigned
ic (3		Unassigned
3as	4		PCI Express Lane 0, default
	5		Unassigned
	6	Fat	Unassigned
	7	Pipes	Unassigned
	8	Region	Unassigned
	9		Unassigned
	10		Unassigned
tor	11		Unassigned
nec	12		Unassigned
on	13		Unassigned
d C	14		Unassigned
ıde	15	Extended	Unassigned
Extended Connector	CLK4/5	Options	Reference Clock 4/5
Ex	17	Region	Unassigned
	18		Unassigned
	19		Unassigned
	20		Unassigned



3.8 Front Panel and LEDs

The **NAMC-ECAT** module is equipped with 4 or 6 LEDs (depending on the number of available ports on the NAMC-ECAT). They are integrated in the RJ45 interface jacks.

Additionally the module contains the standard AMC LEDs and a status indicator LED for the EtherCAT bus.

Figure 7: Front Panel (3 Port)

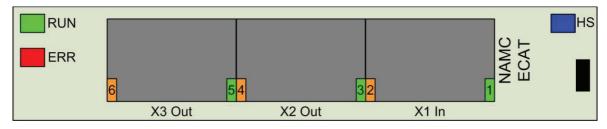
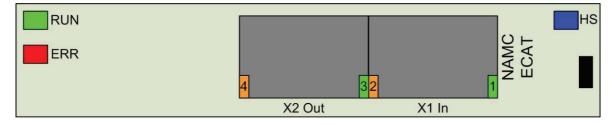


Figure 8: Front Panel (2 Port)



The function of the LEDs is described in the following table:

Table 1: LED Functionality

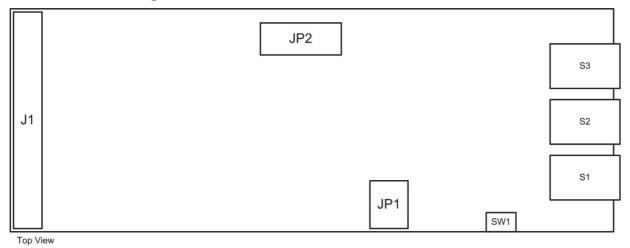
LED	Function
RUN	Status of the EtherCAT State Machine
ERR	AMC Error LED
HS	AMC Hot swap LED
1	Link / Activity LED on port 1
2	port receive error LED on port 1
3	Link / Activity LED on port 2
4	port receive error LED on port 2
5	Link / Activity LED on port 2
6	port receive error LED on port 2



4 Connectors

4.1 Connector Overview

Figure 9: Connectors of the NAMC-ECAT



Please refer to the following tables to look up the connector pin assignment of the NAMC-ECAT.



4.2 AMC Connector J1

Table 2: AMC Connector J1

Pin No.	AMC-Signal	AMC-Signal	Pin No.
1	GND	GND	170
2	PWR	TDI	169
3	/PS1	TDO	168
4	PWR_IPMB	/TRST	167
5	GA0	TMS	166
6	RESVD	TCK	165
7	GND	GND	164
8	RESVD	/SPISEL	163
9	PWR	SPICLK	162
10	GND	GND	161
11	XLINK1 P	SPIMOSI	160
12	XLINK1_N	SPIMISO	159
13	GND	GND	158
14	RLINK1_P	PORT19TX_P	157
15	RLINK1 N	PORT19TX N	156
16	GND	GND	155
17	GA1	PORT19RX P	154
18	PWR	PORT19RX N	153
19	GND	GND	152
20	XLINK2 P	PORT18TX P	151
21	XLINK2 N	PORT18TX N	150
22	GND	GND	149
23	RLINK2 P	PORT18RX P	148
24	RLINK2 N	PORT18RX N	147
25	GND	GND	146
26	GA2	NC	145
27	PWR	NC	144
28	GND	GND	143
29	NC	NC	142
30	NC	NC	141
31	GND	GND	140
32	NC	NC	139
33	NC	NC	138
34	GND	GND	137
35	NC	NC	136
36	NC	NC	135
37	GND	GND	134



Pin No.	AMC-Signal	AMC-Signal	Pin No.
38	NC	NC	133
39	NC	NC	132
40	GND	GND	131
41	/ENABLE	NC	130
42	PWR	NC	129
43	GND	GND	128
44	PETO P P4	RESVD	127
45	PETO N P4	TDM REF	126
46	GND	GND	125
47	PER0 P P4	TDM_FS	124
48	PER0 N P4	TDM CLK	123
49	GND	GND	122
50	NC	TDM7	121
51	NC	TDM6	120
52	GND	GND	119
53	PER1 P	TDM5	118
54	PER1 N	TDM4	117
55	GND	GND	116
56	IPMB SCL	TDM3	115
57	PWR	TDM2	114
58	GND	GND	113
59	NC	TDM1	112
60	NC	TDM0	111
61	GND	GND	110
62	NC	NC	109
63	NC	NC	108
64	GND	GND	107
65	NC	NC	106
66	NC	NC	105
67	GND	GND	104
68	NC	NC	103
69	NC	NC	102
70	GND	GND	101
71	IPMB SDA	NC	100
72	PWR	NC	99
73	GND	GND	98
74	CLK 1 P	NC	97
75	CLK 1 N	NC	96
76	GND	GND	95
77	CLK 2 P	NC	94
78	CLK_2_N	NC	93



Pin No.	AMC-Signal	AMC-Signal	Pin No.
79	GND	GND	92
80	CLK_3_P	PETO_P_P8	91
81	CLK_3_N	PETO_N_P8	90
82	GND	GND	89
83	/PS0	PERO_P_P8	88
84	PWR	PER0_N_P8	87
85	GND	GND	86

4.3 Connector JP1: IPMI-μC Programming Port

Connector JP1 connects the programming-port of the Atmel µC device.

Table 1: Atmel Programming Port

Pin No.	Signal
1	MISO
2	VCC_IPMB
3	SCK
4	MOSI
5	/RST_IMPI
6	GND

4.4 Connector JP2: Lattice FPGA programming port

Connector JP2 connects the JTAG- or programming-port of the Lattice FPGA device.

Table 1: Lattice programming port

Pin No.	Signal	Signal	Pin No.
1	+3.3V	TDO	2
3	TDI	/PROGRAM	4
5	nc	TMS	6
7	GND	TCK	8
9	DONE_LAT	/INIT_LAT	10



4.5 Hot Swap Switch SW1

Switch SW1 is used to support hot swapping of the module. It conforms to PICMG AMC.0.

4.6 The Front Panel Connectors (S1 – S3)

4.6.1 The Ethernet Connector S1

Table 2: shows the pin assignment of RJ45-connector S1. This connector carries the 100BaseT signals of the EtherCAT interface.

Table 2: Pin Assignment of the Front-panel Connectors S1 (Ethernet)

Pin No.	Signal	Signal	Pin No.
1	TX0+	CT	2
3	TX0-	RX0+	4
5	CT	RX0-	6
7	nc	GND	8
9	LED1_A	LED1_K	10
11	LED2_A	LED2_K	12

4.6.2 The Ethernet Connector S2

Table 2: shows the pin assignment of RJ45-connector S2. This connector carries the 100BaseT signals of the EtherCAT interface.

Table 3: Pin Assignment of the Front-panel Connectors S2 (Ethernet)

Pin No.	Signal	Signal	Pin No.	
1	TX1+	CT	2	
3	TX1-	RX1+	4	
5	CT	RX1-	6	
7	nc	GND	8	
9	LED1_A	LED1_K	10	
11	LED2_A	LED2_K	12	



4.6.3 The Ethernet Connector S3

Table 2: shows the pin assignment of RJ45-connector S3. This connector carries the 100BaseT signals of the EtherCAT interface.

Table 4: Pin Assignment of the Front-panel Connectors S3 (Ethernet)

Pin No.	Signal	Signal	Pin No.	
1	TX2+	CT	2	
3	TX2-	RX2+	4	
5	CT	RX2-	6	
7	nc	GND	8	
9	LED1_A	LED1_K	10	
11	LED2_A	LED2_K	12	



5 NAMC-ECAT Programming Notes

The table below shows the memory map for the logical sub-blocks of the design. Refer to the following sub-chapters for detailed information.

Table 1: FPGA Memory Map

Address Offset	Logical Block
0x00000	General Purpose Status (read-only)
0x00100	General Purpose Registers
0x01000	SPI interface to FPGA PROM
0x02000	SPI interface to MMC (Atmel)
0x10000	μC interface to EtherCAT Slave Controller

The FPGA-Design consists of two main blocks:

- Misc. board control- and status registers, and a register-interface to access the FPGA's PROM and the MMC
- μController interface to access the EtherCAT slave controller registers (for configuration and process data exchange)

5.1.1 FPGA GP Registers/Status

This chapter describes the basic board control registers implemented within the FPGA. Further register description will follow up in future versions of this manual.

5.1.1.1 PCB Version Register

The Version Register holds the PCB Revision, encoded in two nibbles.

Table 1: PCB Version Register

PCB Version - Address 0x00							
Default value 0x0011							
Bit	Bit 158 74 30						
Access	R	R	R				
Func	reserved	Version Major	Version Minor				



5.1.1.2 FPGA Version Register

The Version Register holds the FPGA Revision, encoded in two nibbles.

Table 1: FPGA Version Register

FPGA Version - Address 0x02					
Default value 0x0010					
Bit 158 74 30					
Access	R	R	R		
Func	reserved	Version Major	Version Minor		

5.1.1.3 FPGA ID_1 Register

This read only register can be used by the device driver to probe register access.

Table 2: FPGA ID 1 Register

FPGA ID_1 - Address 0x04		
Default value 0xAA55		
Bit	150	
Access	R	
Func	ID_1	

5.1.1.4 FPGA ID_2 Register

This read only register can be used by the device driver to probe register access.

Table 3: FPGA ID 2 Register

FPGA ID_2 - Address 0x06		
Default value 0xDEAD		
Bit	150	
Access	R	
Func	ID_2	

5.1.1.5 FPGA BOARD_ID Register

This read only register can be used by the device driver to probe register access. It holds the N.A.T. internal board-id of the NAMC-ECAT.

Table 4: FPGA BOARD ID Register

FPGA BOARD_ID - Address 0x08		
Default value 0x0B0f		
Bit	150	
Access	R	
Func	BOARD_ID	



5.1.1.6 FPGA Reset Register

The Reset Register is used to trigger a reset to the whole FPGA logic, FPGA blocks, or external devices. Writing a '1' to a bit triggers the reset. After reset, the bit is self-cleared to '0'.

Table 5: FPGA Reset Register

	Reset – Address Offset 0x100							
	Default value 0x0000							
Bit	3it 15 6 5 4 3 2 1 0						0	
Access	Access R/W R/W<						R/W	
Func	-	-	-	-	-	-	-	ESC

5.1.1.7 SPI interface register to FPGA PROM

This chapter will be completed in a later version of the User's Manual. For the time being, contact N.A.T. for further information.

5.1.1.8 SPI interface register to Atmel

This chapter will be completed in a later version of the User's Manual. For the time being, contact N.A.T. for further information.

5.1.1.9 ESC Register

The ESC registers are divided into registers for configuration and control and registers for process data exchange. The start address for the access on the ESC register is 0x10000. The table below shows the memory map. For more information regarding read and write accesses on these registers please consider the ESC data sheet [1].

Table 1: ESC Register

Address Offset	Logical Block
0x10000	Register for ESC configuration and control
0x11000	Register for ESC process data exchange



6 Known Bugs / Restrictions

none



Appendix A: Reference Documentation

- [1] Beckhoff, ET1100 Hardware Data Sheet, Rev. 1.5
- [2] Broadcom, BCM5241 Data Sheet, Document 5241-DS12-R
- [3] Atmel, AT24C128/256 Data Sheet, Rev. 0670J-SEEPR-4/1/03
- [4] Atmel, Atmega16/16L Product Data, Rev. 2466C-03/02
- [5] Lattice, ECP2/M Handbook, Version 04.2
- [6] PLX Technology, PEX8112-AA, PCI Express to PCI Bridge, Data Book, Version 1.2



Appendix B: Document's History

Revision	Date	Description	Author
1.0	15.06.2010	initial revision	rm
1.1	17.05.2013	Address, phone and fax updated, words updated	fh